Minimum founding populations for the first peopling of Sahul

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The timing, context and nature of the first people to enter Sahul is still poorly understood owing to a fragmented archaeological record. However, quantifying the plausible demographic context of this founding population is essential to determine how and why the initial peopling of Sahul occurred. We developed a stochastic, age-structured model using demographic rates from hunter-gatherer societies, and relative carrying capacity hindcasted with LOVECLIM's net primary productivity for northern Sahul. We projected these populations to determine the resilience and minimum sizes required to avoid extinction. A census founding population of between 1,300 and 1,550 individuals was necessary to maintain a quasi-extinction threshold of ≤ 0.1 . This minimum founding population could have arrived at a single point in time, or through multiple voyages of \geq 130 people over ~700-900 years. This result shows that substantial population amalgamation in Sunda and Wallacea in Marine Isotope Stages 3-4 provided the conditions for the successful, large-scale and probably planned peopling of Sahul.

n understanding of the demographic circumstances and ecological repercussions of the arrival of the first people to Sahul (mainland Australia, Tasmania and New Guinea joined at times of lower sea level) in the Late Pleistocene remains elusive¹⁻³. Some have previously proposed that the first peopling arose from only small family groups consisting of <150 people⁴⁻⁷, while more recent human behavioural ecology models suggest that several hundred people would have been required for long-term survival7. These estimates are largely speculative, but genomic research and radiocarbon-inferred demographic modelling support the larger values, and imply that population sizes of 1,000-3,000 people were more likely⁸⁻¹⁰. Quantifying the plausible demography of the first humans (that is, the rate of population changes relative to regional carrying capacity, and the duration over which populations could have persisted at low density following first arrival) is essential to ascertain the extent to which increasing human populations could have altered their environments. Quantifying demographic transitions can also potentially help to interpret the likelihood of discovering archaeological evidence, given the persistence of small human populations over extended windows of time so long ago⁶.

The oldest archaeological evidence claimed in Australia dates to 65.0 ± 5.7 thousand years ago (ka) (95% confidence interval (CI)) for the Madjedbebe rockshelter in Arnhem Land^{11,12}, and an increasing number of early sites have been reported dating to around or before 47 ka^{13-21} . We therefore take the broad interval of 65-50 ka as the probable arrival window of people into Sahul. Arrival probably occurred somewhere in the northern regions of Sahul, closest to the islands of Wallacea in the Timor Sea, the Arafura Sea, and across the Torres Strait and Carpentarian Plain during times of lower sea levels^{22–27}.

However, given that only a few archaeological sites from the north have revealed cultural remains within the putative arrival window, and that ancient DNA is poorly preserved in this region of the world, it is difficult to estimate when and where enough people first arrived in Australia to produce one of the longest standing, successful human populations in the world outside Africa-a population that went on to adapt successfully and populate the entire continent over the following several thousand years^{10,28,29}. Recent studies have modelled plausible routes, and therefore the potential geographic locations that would have supported a successful migration to Australia²²⁻²⁷, but the numbers and diversity of humans who first arrived on the continent remain largely unknown^{10,28,29}. Fundamentally then, the size and migration patterns of founding populations (that is, whether arrival was accidental by a small band of hunter-gatherers, or something larger scale and more complex) directly contributes to our understanding of modern human societies at this time, and how the peopling of Sahul fits into this broader story.

To determine the probable range of these unknown demographic conditions, we developed a stochastic, age-structured demographic model for ancient Australians to: (1) estimate the minimum size of a founding population that would be required to avoid a high risk of extinction at the time of first arrival; and (2) calculate the interval and frequency of smaller introductions that would maintain a low probability of extinction over the initial arrival window (65–50 ka). Our model is based on realistic estimates and assumptions of hunter-gatherer demography, as well as a reconstruction of the carrying capacity based on hindcasted estimates of net primary production. We hypothesize that several thousand individuals arriving over a defined period within several centuries were required to

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Fig. 1] Estimating quasi-extinction probability for the first Sahul population. a, Probability of quasi-extinction (<25 females or <50 total individuals), expressed as a function of the size of a one-off founding population (*n*) according to 10,000 runs of the stochastic demographic model. The dashed black line indicates the probability decay curve assuming that the year of initial arrival fell between 65 and 55 ka. The grey line is the curve derived from an initial arrival window of 60-50 ka. The shaded n_{min} area indicates the range of minimum founding population sizes giving *P*(quasi-extinction) = ~0.1, which we applied in the simulations shown in **b** (symbolized by the downward-pointing curved arrow from **a** to **b**). **b**, *P*(quasi-extinction) as a function of an increasing interval between regularly spaced arrival events (10, 20, 30, ... 300 years), each comprising one-tenth of the total founding population of 650-775 females (black line, regular interval), or as a function of randomly sampled introduced-population sizes and randomly sampled intervals averaging 10, 20, 30, ... 300 years (grey line, random interval). Also shown are the least-squares linear-regression *R*² coefficients for both trajectories. The circles indicate example projections, as shown in **c** and **d**. **c**, An example 50-year constant-interval simulation occurring over 500 years (int_c). The upper and lower lines indicate the 95% CIs of the median (darker middle line) projected population size (*n*). **d**, An example 100-year random-interval simulation occurring over an average of 1,000 years (int_c). The lines are as described in **c**.

avoid extinction within the first 100 human generations following first arrival.

Results

Deterministic matrix properties. The base matrix M using the Siler hazard model³⁰ to estimate the survival vector (Supplementary Fig. 1) produced a dominant eigenvalue $\lambda = 1.0037$, which equates to an instantaneous rate of population change (r)=0.0037. Applying different underlying parameters for the Siler hazard model for 'average forager-horticulturist' and 'Northern Territory Aborigines'³¹ increased the base matrix's dominant eigenvalue $(\lambda = 1.0085 \text{ and } 1.0201, \text{ respectively})$. However, given the assumed hunter-gatherer mode of subsistence during the time of initial arrival into Sahul, and the rapid rate of increase in the Aboriginal population data (collected 1958–1960) that probably underreported infant deaths³¹, we maintained the lowest λ for the 'average hunter-gatherer' scenario in all subsequent simulations. This model gives a ratio of the number of female offspring in year

t+1 to the number born in the previous year (R_0) of 1.11, and a mean generation time (*G*) of 27.7 years, which agrees well with the ~29-year generation length estimated from genealogy-based studies of hunter-gatherers³². Life expectancy (e_x) according to this model increases from around 31 to a maximum 42 years between the ages of 1 and 5 years old, after which it declines linearly with age (Supplementary Fig. 1). Thus, a 20-year-old has $e_x = 35$ (additional) years of expected life, and a 40-year-old has $e_x = 24$ additional years of expected life (Supplementary Fig. 1).

Minimum founding population size. The probability of quasiextinction (n < 50 individuals or <25 females) stabilizes at around 0.1 over 100 generations for founding population sizes of 1,300–1,550 individuals (Fig. 1), or between 650 and 775 females assuming an equal sex ratio. There is quantitatively no difference between the two curves assuming different timings of first arrival (that is, 65–55 ka or 60–50 ka; Fig. 1a). The relationship between the probability of quasi-extinction and founding population size takes into consideration all uncertainty



Fig. 2 | Change in net primary production and indicative human carrying capacity. a, Net primary production hindcasted by the LOVECLIM⁵⁰ Earth system mode^[5], showing an example for Sahul at 60,000 ka. The outlined box at the top in **a** indicates the $1^{\circ} \times 1^{\circ}$ grid cells (n = 166) covering 'northern' Sahul (latitude: $0^{\circ}-14^{\circ}$ S) used to derive the relative human carrying capacity (K) used in subsequent analyses (see Methods). **b**, The shaded area indicates the range between the 25th and 75th percentiles of K from 120 ka to the present, expressed in terms of total human population size (n). **c**, Same as in **b**, but focusing on the period of first arrival, 65–55 ka (as indicated by vertical lines in **b**).

associated with the hindcasted carrying capacity K (Fig. 2), start year and error (process and sampling) in the Leslie matrix's demographicrate elements (survival and fertility; Supplementary Figs. 1 and 2), but it assumes a single-year introduction event (that is, all founding individuals arrive during the same year).

Taking this range (650–775 founding females) and dividing it by 10, such that one-tenth of this minimum arrive at incrementing intervals from 10–200 years, the probability of extinction rises approximately linearly with increasing interval length (Fig. 1b), but remains near 0.1 for up to about 70-year intervals (that is, 65–75 founding females arriving every 70 years over 7 centuries) (Fig. 1b). Assuming a non-regular (random) arrival frequency and a Gaussian-resampled arriving population size, the rate of increase in P(quasi-extinction) is also linear, but less than the rate based on a regular arrival frequency (Fig. 1b); for the latter, however, the probability remains ~0.1 up to approximately 70- to 90-year arrival intervals on average.

Global sensitivity analysis. The boosted-regression tree emulator for the 12-dimension, Latin hypercube-sampled parameter space indicated that the dominant (negative) influence on the probability of quasi-extinction was variation in age-independent mortality $(b_1$ in the Siler hazard model) (Supplementary Fig. 3). Total fertility (F) had the next-highest relative (negative) influence, followed by the (positive) influence of infant mortality rate (a_1) , and the (positive) influence of the rate of mortality decline (a_2) , with all other parameters considered having relatively weak or no detectable influence on P(quasi-extinction) (Supplementary Fig. 3).

Discussion

Discerning the plausible demographic conditions of human arrival to Australia is problematic because of the deep age of the event(s), differential preservation of archaeological material since that time, limited ancient DNA evidence, uncertainties associated with dating, taphonomic biases, and incomplete temporal and spatial coverage of samples. However, stochastic demographic models built from realistic human demographic rates, hindcasts of indicative regional carrying capacity, and relevant archaeological and genetic data to guide inference, return ecologically credible conditions. Future archaeological and palaeoecological data could also potentially exclude ecologically unrealistic hypotheses. Using the best data available (while acknowledging that having more is desirable), our models estimate that as few as ~650 females (representing ~1,300 individuals in total) arriving in small groups (~130 each) over as many as 700-900 years would be sufficient to avoid a high probability of extinction during the probable environmental conditions that dominated northern Sahul between 65 and 50 ka.

These numbers of people—whether ~130 arriving at semiregular intervals¹⁰ over a long period or 1,300 at one time—are substantively larger than ethnographically observed Aboriginal hunter-gatherers, except during larger ceremonial gatherings³³. This therefore suggests that large populations were probably present in Wallacea during Marine Isotope Stages 3 (29–57ka) and possibly 4 (57–71ka) at much greater densities than their counterparts in Australia for much of the past 50ka—or that smaller hunter-gatherer groups banded together to make one or more migrations to Sahul. In either case, our results imply that modern human populations at that time

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were sufficiently socially integrated³⁴ to be able to achieve the construction and successful voyaging of multiple ocean-going vessels²⁷. This further suggests cognitive ability and planning, and probably deliberate migration given the numbers of people involved^{25,27}.

Unlike the mostly genetics-based estimates of founding effective population size (n_e) that cannot easily discern an associated census population size (n_c) , our estimates provide a value of n_c that does not necessarily imply random breeding among all individuals alive. This is because we indirectly accounted for potential inbreeding depression that could arise from non-random breeding by including a catastrophic mortality function that scales with generation time³⁵. This added stochasticity thus more closely aligns with the ecological reality of a population constrained not only by environmental variability, but also by demographic and genetic stochasticity. Furthermore, genetics-based estimates of n_e cannot typically identify fine-scale details of multiple arrival events over the period of several human generations. Thus, our resampling approach also provides the unique minimum interval over which successive human arrivals could have occurred. This does not necessarily imply that arrivals of small groups of humans occurred over the 700- to 900-year (that is, 25- to 32-generation) window we estimated; rather, it merely indicates that the extinction probability remained low within this window. This does not therefore preclude the occurrence of larger and more frequent introduction pulses over longer time frames.

Of course, our model predictions do rely on several unmeasurable parameters, not least of which are the types of survival and fertility schedules experienced by the first humans to enter Sahul over 50-65 ka. Indeed, our global sensitivity analysis showed that our results are most sensitive to variation in the underlying patterns of initial and environmentally stochastic survival probabilities estimated with the Siler hazard model, as well as total fertility (Supplementary Fig. 3). Nonetheless, our adoption of 'average' hunter-gatherer demographic rates appears reasonable and probably does not overestimate infant survival³¹. We also assumed that carrying capacity was proportional to net primary productivity³⁶, although it is also plausible that ancient humans struck a compromise between high productivity and ease of passage and/or visibility to hunt prey by tending towards ecotones of mid-range productivity³⁷. Had the ecological conditions at the time of first arrival favoured higher vital rates, the true population size might have been larger than our estimates suggest; however, we are concerned here solely with estimating the minimum viable population size derived from conservative, yet realistic, demographic parameters.

More importantly, assessments of relative carrying capacity appeared to have only weak effects on our model predictions, particularly given the near-identical form of the quasi-extinction/ founding-population-size curve for the introduction windows of 65–55 and 60–50 ka (Fig. 1), as well as the low influence of the density-feedback survival modifier (S_{mod}) and nadir population density (D_{min}) identified in the global sensitivity analysis (Supplementary Fig. 3). Thus, the specific choice of carrying capacity (expressed as the total number of humans permitted to occupy the landscape) and the arrival window per se have little bearing on our conclusions. This outcome holds even if carrying capacities were, in fact, higher than we assumed because of potentially higher prey availability at initial arrival relative to later periods when many megafauna species were no longer present^{1,2} (although regional extirpation times of megafauna are still highly uncertain, especially for northern Australia).

Furthermore, our estimate of ~1,300 minimum founding individuals arriving within 25–32 generations agrees well with geneticsbased estimates of total effective population size. For example, there are n_e estimates of populations as small as 170–230 Maori women based on mitochondrial DNA for the peopling of New Zealand³⁸, as few as 70 individuals based on mitochondrial and Y-chromosome DNA for the peopling of the New World from Asia³⁹, and 150 female Yakuts in north-eastern Siberia based on mitochondrial DNA⁴⁰. While the true $n_e:n_c$ ratio for each of these populations is unknown, if we assume an average of ~0.10 based on a multispecies assessment⁴¹, the previously cited values of n_e would equate to an n_c of 700–4,600 individuals; the resemblance to our demographically based estimates is therefore striking. Previous studies of Aboriginal Australian DNA posited that at least 36-50 founding females were required to establish known Australian mitochondrial diversity (estimated from 4-5 founding females for each of the 9-10 haplogroups)²⁵. This range is likely to be a conservative minimum boundary, as founding populations with limited female diversity (<10 per haplogroup) have little chance of survival⁴². Again, assuming that $n_e:n_c=0.1$ gives a value of n_c ranging from 720 to 1,000, our results are not at odds with this argument, although our model conservatively suggests that the minimum number of females per haplogroup would probably have been higher. However, such estimates assume that known Australian haplogroups today represent the total mitochondrial diversity present during the period of first arrival, and this assumption is likely to be inaccurate.

In summary, our demographic models quantifying the ecologically plausible demographic context of the first humans to people Australia now allow for exploration of other questions regarding human adaptations and technological developments during this period, which could have assisted in successfully populating Sahul. Possibly driven in part by the amalgamation of people in Sunda and Wallacea at this time, more research describing the antecedent conditions in those regions would assist greatly in describing the source population(s), and possibly reveal the impetus for subsequent directed migrations^{22–27} to Sahul.

Methods

Demographic rates. Our first requirement was to estimate realistic demographic rates (survival, fertility and longevity) for ancient Australians, to parameterize an age-structured model. For survival, we used the five-parameter Siler hazard model³⁰ to estimate the age (x)-specific proportion of surviving individuals (l_x), which incorporates survival schedules for three stages: immature, mature and senescent individuals within the population:

$$l_x = e^{\left(\frac{-a_1}{b_1}\right)(1-e^{-b_1x})} e^{-a_2x} e^{\left(\frac{a_3}{b_3}\right)(1-e^{b_3x})}$$
(1)

where a_1 is the initial infant mortality (also described elsewhere as α_i), b_1 is the rate of mortality decline in immatures, a_2 is the age-independent mortality due to environmental influence, a_3 is the initial adult mortality and b_3 is the rate of mortality increase (senescence). We used the average 'hunter-gatherer' parameter estimates from Gurven and Kaplan³¹ (based on modern populations and compared with palaeo-demography) to construct l_x ($a_1 = 0.422$; $b_1 = 1.131$; $a_2 = 0.013$; $a_3 = 0.000147$; $b_3 = 0.086$), then calculated the age-specific survival (S_x) for life tables (Supplementary Fig. 1) as:

$$S_x = 1 - \frac{(l_x - l_{x+1})}{l_x}$$
(2)

From the l_x vector, we also calculated the age-specific life expectancy (e_x) as:

$$e_x = \sum_{i=1}^n \left(\frac{(l_x + l_{x+1})}{2} \right)_i$$

For fertility, we first estimated a fertility schedule based on age at primiparity estimates for 22 modern hunter-gatherer groups⁴³, taking the average and 95% confidence interval (CI) limits as indicators of the onset of reproduction in such societies. This gave a mean age of 19 years for primiparity among women (95% CI: 16–24). Further evidence of reproductive senescence and menopause in hunter-gatherer women suggests that hunter-gatherer societies included many women beyond their fertile years^{44–46}. Thus, the onset of reproduction and the implied fertility decline compare well with the global average fertility schedule of modern *Homo sapiens*⁴⁷. For total fertility (*F*), we used the value of 4.69 births (that is, 2.35 daughters) for the !Kung hunter-gatherer society⁴⁸ (Supplementary Fig. 2).

Age-structured (Leslie) matrix model. From these estimated demographic rates, we constructed a prebreeding, 81 (i) × 81 (j) element (representing ages from 0–80 years old), Leslie projection matrix (M) for females only (males are demographically irrelevant in this context assuming equal sex ratios), multiplying

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a population vector **n** to estimate the total population size at each forecast time step¹⁹. Thus, we used a longevity (ω) of 80 years based on cross-cultural examination of hunter-gatherer societies³¹, which was itself founded on the modal adult death of about 70 years. Fertilities (m_x) occupied the first row of the matrix, survival probabilities (S_x) occupied the subdiagonal, and we set the final diagonal transition probability (M_{i_ij}) to zero. We projected the M**n** combinations for each iteration of the simulation (see below) to obtain the yearly total population size.

Carrying capacity. In the absence of measured compensatory density-feedback mechanisms for ancient humans, we used a hypothetical reduction in the survival vector by constructing a theoretical carrying capacity (K) built from a hindcasted estimate of net primary production based on the LOVECLIM climate reconstruction⁵⁰. LOVECLIM is a three-dimensional Earth system model of intermediate complexity⁵¹ (that is, its spatial resolution is coarser than that of stateof-the-art general circulation models, and its representation of physical processes is simpler) that has been validated extensively for the past few glacial cycles and for many regions of the world⁵²⁻⁵⁵. LOVECLIM includes representations of the atmosphere, ocean and sea ice, land surface (including vegetation), ice sheets, icebergs and the carbon cycle, and produces climates over the past 120 ka in 1,000year snapshots downscaled (using a bilinear interpolation)56,57 at a spatial resolution of 1°×1°. For each grid cell and each 1,000-year snapshot, we extracted the mean annual temperature, mean annual precipitation, freshwater availability (that is, evapotranspiration minus precipitation), bottom (soil) moisture, desert fraction and net primary production⁵². The candidate K output variables (freshwater availability, bottom moisture, desert fraction and net primary production) for northern Australia (see below) were highly correlated (Spearman's $|\rho| \ge 0.842$; Supplementary Table 1), so we chose net primary production (kgC m⁻²yr⁻¹) as the comprehensive indicator of relative carrying capacity through time. Indeed, regional carrying capacity is correlated with net primary production for many species, including humans58-62. To focus on the region of interest, we took all Sahul (Australia, New Guinea and Tasmania) 1°×1° grid cells from the equator (0°) to 14°S latitude to represent 'northern' Sahul (including New Guinea, most of the top end of the Northern Territory and Cape York Peninsula) (Fig. 2a), and calculated the 25th and 75th percentiles for net primary production across this region; from within this quartile range, we stochastically sampled annual net primary production per projection iteration (see below).

To translate net primary production into a carrying capacity expressed in units of humans the landscape was capable of supporting, we used data derived from archaeological sites and the assumption of a putative population low (nadir) that occurred during and immediately after the Last Glacial Maximum (23-18ka)63-6 when conditions were cooler than today, and much (but not all67-70) of the continent was drier⁷¹⁻⁷⁸. Demographic reconstructions based on the spatial distribution of dated archaeological sites suggest that up to 80% of Australia could have been abandoned or experienced reduced occupation at some point during this interval65, or at least a major spatial thinning of populations (perhaps as much as 60%) during this period⁹. From these demographic reconstructions, we set the baseline population size at the Last Glacial Maximum at 47,000 people continent wide79. This figure is based on an estimated area of habitable land⁷⁹ for Sahul of 9.4 million km² and a population density⁶⁵ of 0.005 individuals km⁻², which is similar to historical estimates of population densities for Australian deserts⁸⁰. We recognize that inferences of past population size are subject to many uncertainties66,81-84 and note accordingly that our model results are not critically dependent on the above input values (see the global sensitivity analysis and Supplementary Fig. 3).

From this putative population low at or around the Last Glacial Maximum, we back-tracked to the window of first arrival to estimate a relative carrying capacity for this period. We then scaled the relative net primary production curve by first adding the absolute minimum 25th percentile to each annual value, and then dividing by the maximum median value. To these scaled annual net primary production values, we multiplied by 47,000 people to provide an annual K in units of individual people (Fig. 2b). For the founding period of interest (65-50 ka), this translates into a minimum K of 69,230-111,329 individuals (25th-75th percentile limits) at 55 ka, and a maximum K of 82,297-158,645 individuals (25th-75th percentile limits) from 63-62 ka (Fig. 2c). We also reproduced the analysis with a starting window between 60 and 50 ka, assuming instead a later date of first arrival (see Results). It is important to understand that the precise timing of the putative population nadir is irrelevant from the perspective of the mathematical reconstruction of the K series, as long as a nadir occurred at some point after first arrival. Also, the specific K conditions at time of first arrival had little effect on our model outputs (see Results).

Compensatory density feedback. When the projected population exceeded the resampled net primary production *K* in person units that year, we multiplied the β -resampled survival vector (see below) by a multiplier of 0.98 (S_{mod}) to impose a compensatory feedback mechanism. This is because the base *M* matrix had a low dominant eigenvalue (that is, rate of population change; see Results), so this compensatory density-feedback mechanism amounts to a 2% drop in average survival each time total abundance exceeded that time step's sampled *K* value. This acted to keep the projections from growing exponentially over the 100 human generations.

Catastrophic mortality events. We also included a catastrophic die-off function in the simulations to account for the probability of catastrophic mortality events (*C*) scaling to generation length among vertebrates³⁵:

 $C = \frac{P_{\rm C}}{G}$

where $P_{\rm c}$ is the probability of catastrophe (set at 0.14)³⁵ and *G* is the mean generation time (27.6 years), as calculated from the deterministic matrix $M^{\rm 49}$. Once invoked at probability *C* for any iteration of the model (see below), we halved the survival vector to induce a 50% mortality (*d*) event for that year⁸⁵. This was based on the definition of a catastrophe as "... any 1 year peak-to-trough decline in estimated numbers of 50% or greater"³⁵.

Stochastic projections. We conservatively sampled the start date for each of 10,000 projection iterations using a stochastic uniform sampler between 65 and 50 ka (we aimed to use the full uncertainty of *K* during the approximate window of first arrival). We thus had a different, randomly selected start year for the 100 generations projected into the future (that is, from 65–50 ka towards the present), based on the stochastically sampled *M* matrix elements. Here, we defined a function to estimate the shape parameters of a β function, and then randomly β -resampled each element of the survival vector for each year of the projection (assuming an arbitrary $\sigma_s = 5\%$ standard deviation on survival probability). For the fertility vector, we used a random Gaussian resampler for the total (female) fertility *F* described above, based also on an arbitrary 5% standard deviation.

Founding population size. We applied a starting population size from 50–1,000 females in increments of 50, and calculated the probability of quasi-extinction as the number of iterations per founding population size, where at least one projected annual total population size fell below a quasi-extinction threshold (*Q*) of 50 individuals (that is, 25 females, assuming equal sex ratios). This was based on the minimum size below which a population cannot avoid inbreeding depression (although it could be twice as high as this⁸⁶, so our approach was conservative).

To estimate a realistic extinction risk, we must borrow from the ecological concept of minimum viable population size87. Here, there is a rising consensus that several thousand individuals are normally required to avoid inbreeding depression, thereby maintaining evolutionary potential⁸⁶, and thus avoiding extinction⁸⁸. This is because non-random breeding generally equates to lower effective population sizes (n_e) than census population sizes $(n_e)^{41}$. In the case of founding Homo species populations, various population genetic approaches (in some instances combined with archaeological evidence9) have estimated minimum founder population sizes from 80 to several thousand effective individuals^{9,39,89-93}. However, the relationship between n_e and n_c is complex and variable⁴¹, depending in part on the time frame over which the data are collected and measured94. Even with the current lack of reliable estimates of n_e for the first people to arrive in Australia, the uncertainty associated with $n_e:n_e$ ratios means that another approach is required to estimate both the probable initial population size of founding humans arriving over 50 ka and the period during which these people probably arrived in Australia and became a genetically interacting and viable founding population.

However, this approach assumes an instantaneous arrival of the entire founding population in year 1, which is probably an unrealistic representation of the more likely sequence of multiple arrivals of smaller groups over the entire founding 'interval'. To estimate the frequency of smaller introduction events that maintained a low probability of extinction, we resampled 10,000 times the range of the minimum viable population defined in the previous step (that is, the minimum number of total founders maintaining a probability of quasi-extinction of ~0.1). We first assumed that each introduction event represented one-tenth of the total founding population, but that they were spread out by an incrementing interval of decades. Thus, the first introduction frequency was every 10 years (that is, onetenth of the minimum viable founding population arriving every 10 years over one century), the second was every 20 years (one-tenth every 20 years over two centuries), and so on until a frequency of 300 years (that is, one-tenth arriving every 300 years over 3,000 years) (Fig. 1c,d). The resulting frequency-quasiextinction probability relationship thus indicates the frequency at which onetenth of the minimum founding population is required to raise the probability of extinction beyond the level of ~0.1 established in the first step.

However, the reality of an even frequency of identical arriving population sizes is also unlikely, so we added complexity to our model (thus increasing realism) by randomly resampling 10,000 times both the number of introduction events and the frequency between events, such that the latter averaged an incrementing range of decades between events (as above). Here, we randomly resampled the initial introduction event as a random uniform number between 25 females (quasi-extinction threshold) and one-half of the minimum founding population established in the first step. We then randomly resampled the following introduction-population sizes from the remaining number of individuals up to the minimum total founding population size, until we reached the cumulative minimum founding population size. We used a random Gaussian sampler of the same sequence as in the previous step, assuming a 10% standard deviation. Thus, the first frequency was an introduction interval resampled with a mean of 10 years

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and a standard deviation of 1 year, the second was resampled with a mean of 20 years and a standard deviation of 2 years, and so on up to a mean of 200 years between introductions (and the associated 20-year standard deviation).

Global sensitivity analysis. We designed a 'global' sensitivity analysis to provide robust sensitivity measures of the probability of quasi-extinction to variation in the underlying parameters of our stochastic model^{95,96}. We applied a Latin hypercubesampling protocol⁹⁶ of the parameter space assuming a founding population size of 700 females projected over 100 generations. We sampled 12 parameters from a uniform distribution as follows: (1-5) all five parameters used to calculate the Siler hazard model for age-specific survival: a_1 (varying from 0.3–0.5), b_1 (1.0-2.0), a_2 (0.010-0.015), a_3 (1.323×10⁻⁴-1.617×10⁻⁴) and b_3 (0.060-0.095); (6) standard deviation of survival (σ_s) for stochastic resampling (0.025–0.100); (7) density-feedback survival modifier S_{mod} (0.95–0.99); (8) total fertility F (2.1105-2.5795); (9) quasi-extinction threshold Q (13-75 females); (10) probability of catastrophe $P_{\rm C}$ (0.1–0.2); (11) intensity of catastrophic die-offs *d* (0.25–0.75); and (12) nadir population density during/near the Last Glacial Maximum (0.0025-0.010 individuals km⁻²; that is, from half to double the 0.005 value assumed in the model based on archaeological data^{65,79}). To sample using the Latin hypercube protocol, we ran the simulation for 100 iterations, with 1,000 samples from the parameter space. To test the effect of the parameter values on P(quasi-extinction), we used a boosted-regression tree97 emulator with the function gbm.step98 in the dismo R library, setting the error distribution family as Gaussian, the bag fraction to 0.75, the learning rate to 0.01, the tolerance to 0.0001 and the tree complexity to 2 (first-order interactions only). To assess the relative contribution of each sampled parameter to P(quasi-extinction), we present the boosted-regression tree metrics of relative influence%

Reporting Summary. Further information on research design is available in the Nature Research Reporting Summary linked to this article.

Data availability

All data are available for download at github.com/cjabradshaw/SahulHuman.

Code availability

All R code is available for download at github.com/cjabradshaw/SahulHuman.

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Author contributions

C.J.A.B. and F.S. designed the research. C.J.A.B. performed the analysis and sourced the data. C.J.A.B., F.S., S.U., A.N.W. and M.I.B. wrote the paper. All other co-authors contributed substantially to developing the manuscript.

Competing interests

The authors declare no competing interests.

Additional information

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Software and code

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Data collection	All code was written in the R Project for Statistical Computing (www.r-project.org), and is available at https://github.com/cjabradshaw/ SahulHuman
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	Madelling study only no astual specimens were compled specifically in this study (i.e., published data only)	
Research sample	woodening study only, no actual specimens were sampled specifically in this study (i.e., published data only).	
Sampling strategy	'sampling' was done stochastically to achieve Gaussian-like behaviour (10,000 iterations per incrementing scenario value)	
Data collection	No data were collected as such; all data derived from published sources or derived via modelling	
Timing and spatial scale	approximately 60,000 to 45,000 years ago; spatial scale = northern Australia (10 to 18 degrees South latitude)	
Data exclusions	No data excluded	
Reproducibility	We estimated probabilities based on stochastic resampling of the full parameter uncertainties, for which an accompanying global	
	sensitivity analysis is presented.	
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Clinical data

Policy information about <u>clinical studies</u>

All manuscripts should comply with the ICMJE guidelines for publication of clinical research and a completed CONSORT checklist must be included with all submissions.

Clinical trial registration	Provide the trial registration number from ClinicalTrials.gov or an equivalent agency.	
Study protocol	Note where the full trial protocol can be accessed OR if not available, explain why.	
Data collection	Describe the settings and locales of data collection, noting the time periods of recruitment and data collection.	
Outcomes	Describe how you pre-defined primary and secondary outcome measures and how you assessed these measures.	

ChIP-seq

Data deposition

Confirm that both raw and final processed data have been deposited in a public database such as GEO.

Confirm that you have deposited or provided access to graph files (e.g. BED files) for the called peaks.

Data access links May remain private before publication. For "Initial submission" or "Revised version" documents, provide reviewer access links. For your "Final submission" document, provide a link to the deposited data.

Files in database submission	Provide a list of all files available in the database submission.		
Genome browser session (e.g. <u>UCSC</u>)	Provide a link to an anonymized genome browser session for "Initial submission" and "Revised version" documents only, to enable peer review. Write "no longer applicable" for "Final submission" documents.		
Vethodology			
Replicates	Describe the experimental replicates, specifying number, type and replicate agreement.		
Sequencing depth	Describe the sequencing depth for each experiment, providing the total number of reads, uniquely mapped reads, length of reads and whether they were paired- or single-end.		
Antibodies	Describe the antibodies used for the ChIP-seq experiments; as applicable, provide supplier name, catalog number, clone name, and lot number.		
Peak calling parameters	Specify the command line program and parameters used for read mapping and peak calling, including the ChIP, control and index files used.		
Data quality	Describe the methods used to ensure data quality in full detail, including how many peaks are at FDR 5% and above 5-fold enrichment.		
Software	Describe the software used to collect and analyze the ChIP-seq data. For custom code that has been deposited into a community repository, provide accession details.		

Flow Cytometry

Plots

Confirm that:

The axis labels state the marker and fluorochrome used (e.g. CD4-FITC).

- The axis scales are clearly visible. Include numbers along axes only for bottom left plot of group (a 'group' is an analysis of identical markers).
- All plots are contour plots with outliers or pseudocolor plots.

A numerical value for number of cells or percentage (with statistics) is provided.

Methodology

Sample preparation	Describe the sample preparation, detailing the biological source of the cells and any tissue processing steps used.
Instrument	Identify the instrument used for data collection, specifying make and model number.
Software	Describe the software used to collect and analyze the flow cytometry data. For custom code that has been deposited into a community repository, provide accession details.
Cell population abundance	Describe the abundance of the relevant cell populations within post-sort fractions, providing details on the purity of the samples and how it was determined.
Gating strategy	Describe the gating strategy used for all relevant experiments, specifying the preliminary FSC/SSC gates of the starting cell population, indicating where boundaries between "positive" and "negative" staining cell populations are defined.

Tick this box to confirm that a figure exemplifying the gating strategy is provided in the Supplementary Information.

Magnetic resonance imaging

Experimental design

Design type	Indicate task or resting state; event-related or block design.
Design specifications	Specify the number of blocks, trials or experimental units per session and/or subject, and specify the length of each trial or block (if trials are blocked) and interval between trials.
Behavioral performance measures	State number and/or type of variables recorded (e.g. correct button press, response time) and what statistics were used to establish that the subjects were performing the task as expected (e.g. mean, range, and/or standard deviation across subjects).

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Acquisition

Imaging type(s)	Specify: functional, structural, diffusion, perfusion.	
Field strength	Specify in Tesla	
Sequence & imaging parameters	Specify the pulse sequence type (gradient echo, spin echo, etc.), imaging type (EPI, spiral, etc.), field of view, matrix size, slice thickness, orientation and TE/TR/flip angle.	
Area of acquisition	State whether a whole brain scan was used OR define the area of acquisition, describing how the region was determined.	
Diffusion MRI Used	Not used	
Preprocessing		
Preprocessing software	Provide detail on software version and revision number and on specific parameters (model/functions, brain extraction, segmentation, smoothing kernel size, etc.).	
Normalization	If data were normalized/standardized, describe the approach(es): specify linear or non-linear and define image types used for transformation OR indicate that data were not normalized and explain rationale for lack of normalization.	
Normalization template	Describe the template used for normalization/transformation, specifying subject space or group standardized space (e.g. original Talairach, MNI305, ICBM152) OR indicate that the data were not normalized.	
Noise and artifact removal	Describe your procedure(s) for artifact and structured noise removal, specifying motion parameters, tissue signals and physiological signals (heart rate, respiration).	
Volume censoring	Define your software and/or method and criteria for volume censoring, and state the extent of such censoring.	
Statistical modeling & inference		

Model type and settings	Specify type (mass univariate, multivariate, RSA, predictive, etc.) and describe essential details of the model at the first and second levels (e.g. fixed, random or mixed effects; drift or auto-correlation).		
Effect(s) tested	Define precise effect in terms of the task or stimulus conditions instead of psychological concepts and indicate whether ANOVA or factorial designs were used.		
Specify type of analysis: Whole brain ROI-based Both			
Statistic type for inference (See <u>Eklund et al. 2016</u>)	Specify voxel-wise or cluster-wise and report all relevant parameters for cluster-wise methods.		
Correction	Describe the type of correction and how it is obtained for multiple comparisons (e.g. FWE, FDR, permutation or Monte Carlo).		

Models & analysis

n/a Involved in the study		
Functional and/or effective connectivity		
Graph analysis	Graph analysis	
Multivariate modeling or predictive analysis		
Functional and/or effective connectivity	Report the measures of dependence used and the model details (e.g. Pearson correlation, partial correlation, mutual information).	
Graph analysis	Report the dependent variable and connectivity measure, specifying weighted graph or binarized graph, subject- or group-level, and the global and/or node summaries used (e.g. clustering coefficient, efficiency, etc.).	
Multivariate modeling and predictive analysis	Specify independent variables, features extraction and dimension reduction, model, training and evaluation metrics.	